



Resilient Self-Organizing Networks in Multi-Agent Systems via Approximate Random k -Regular Graphs

Zohreh Al Zahra Sanai Dashti*, Diego Deplano*,
Carla Seatzu*, Mauro Franceschelli*

*Department of Electrical and Electronic Engineering, University of Cagliari, Italy

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Outline

- 1 Problem statement and motivation
- 2 Distributed algorithm to self-organize a graph into a k -regular graphs
- 3 Numerical simulations
- 4 Conclusions and future perspectives

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Scenarios



Peer-to-Peer Networks

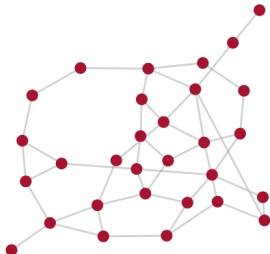


Wireless Sensor Networks

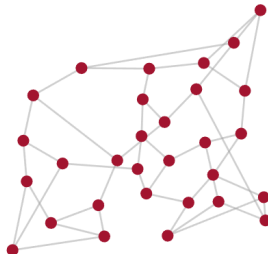


Multi-Robot Systems

k -regular networks



(a) Network with average degree 3



(b) 3-regular network: each node has exactly 3 edges

Same number of edges but different resilience to structural and functional perturbations.

Literature

k -CONNECTED GRAPHS

- Jamakovic and Uhlig, “On the relationship between the algebraic connectivity and graph’s robustness to node and link failures”, in *Conf. Next Gener. Internet Netw.* (2007) pp. 96–102.
- Szczytowski, Khelil, and Suri, “DKM: Distributed k -connectivity maintenance in wireless sensor networks”, in *9th WONS* (2012)

r -ROBUST GRAPHS

- Zhang, Fata, and Sundaram, S, “A notion of robustness in complex networks”, in *IEEE Trans. Control Netw. Syst* (2015)
- Saulnier, Saldana, Prorok, Pappas, and Kumar, “Resilient flocking for mobile robot teams”, in *IEEE Robotics and Automation letters* (2017)
- Guerrero-Bonilla, Prorok, and Kumar, “Formations for resilient robot teams”, in *IEEE Rob. Aut. Lett.* (2017)

k -REGULAR GRAPHS

- Yazicio, Egerstedt, and Shamma, “Decentralized degree regularization for multi-agent networks”, in *52nd IEEE CDC* (2013)
- Yazicio, Egerstedt, and Shamma, “Decentralized formation of random regular graphs for robust multi-agent networks”, in *53rd IEEE CDC* (2014)
- Yazicio, Egerstedt, and Shamma, “Formation of robust multi-agent networks through self-organizing random regular graphs”, in *Trans. on Net. Sc. and Eng.* (2015)

Problem of interest and contribution

Problem

Design a local update rule to iteratively self-organize any connected network into a (*approximate*) *random* k -regular graph under the following assumption:

- each node can add edges to 2-hop neighbors.

Contributions

The proposed procedure has the following advantages with respect to the current literature:

- **Arbitrary order k :** the desired order k of regularity does not depend on the initial graph configuration;
- **Faster convergence:** the desired graph configuration is achieved in fewer steps;
- **Resilience to open networks:** the joining or leaving event the agents do not require the re-initialization of the procedure.

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Problem set-up

undirected network $\rightarrow \mathcal{G} = (\mathcal{V}, \mathcal{E})$

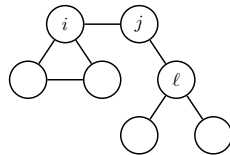
set of agents $\rightarrow \mathcal{V} = \{1, \dots, n\}$

set of connections $\rightarrow \mathcal{E} \subseteq \mathcal{V} \times \mathcal{V}$

1-hop neighbors of agent $i \rightarrow \mathcal{N}_i = \{j \mid (i, j) \in \mathcal{E}\}$

2-hop neighbors of agent $i \rightarrow \mathcal{N}_i^2 = \{\ell \mid \ell \in \mathcal{N}_j, j \in \mathcal{N}_i\}$

degree of agent $i \rightarrow d_i = |\mathcal{N}_i|$



Definition: Random k -regular graphs

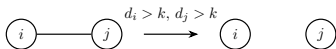
An undirected and connected graph is:

- **k -regular** if each node has exactly k neighbors, i.e., $d_i = k$ for all $i \in \mathcal{V}$;
- **approximate k -regular** if only one node has a number of neighbors different from k ;
- **random k -regular** if it is selected uniformly at random from all k -regular graphs with the same number of nodes.

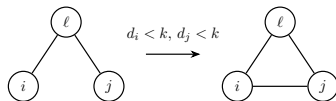
Available actions to the agents

Assumptions

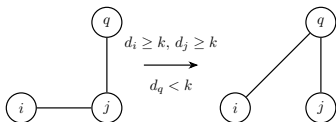
- The initial network is connected
- Each agent can add/delete edges with its 1-hop and 2-hop neighbors



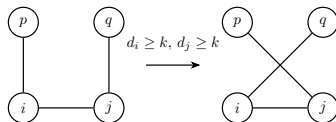
Action (R): Remove an edge



Action (A): Add an edge



Action (M1): Move an edge



Action (M2): Move an edge

Distributed Formation and Maintenance of Random k -Regular Graph

Sketch of Algorithm 1:

(Input): Order $k \in \mathbb{N}_+$ of regularity

(Execution): at each step $t = 1, 2, 3, \dots$

$\mathcal{G} = (\mathcal{V}, \mathcal{E})$ is the current graph

$\mathcal{V}_a \subseteq \mathcal{V}$ is the set of randomly activated nodes

each node $i \in \mathcal{V}_a$ **does**

if *action (A) is feasible* **then**

 | Execute action (A) with a random $j \in \mathcal{N}_i$

else if *action (R) is feasible* **then**

 | Execute it with a random $j \in \mathcal{N}_i^2$

if *action (M1) is feasible* **then**

 | Execute it with random $j \in \mathcal{N}_i, q \in \mathcal{N}_j \setminus \{i\}$

else if *action (M2) is feasible* **then**

 | Execute it with random $j \in \mathcal{N}_i, q \in \mathcal{N}_j \setminus \{i\}, p \in \mathcal{N}_i \setminus \{j\}$

Main results

Consider a network with a fixed number of agents that implements Algorithm 1 and the metric

$$f(\mathcal{G}, k) = \left\| \max_{i \in \mathcal{V}} \{d_i\} - k \right\| + \left\| k - \min_{i \in \mathcal{V}} \{d_i\} \right\|.$$

For any order $k \geq 2$, if the graph is initially connected graph and remains connected thereafter, then at each step it holds that:

- i)* the metric $f(\mathcal{G}, k)$ is non-increasing;
- ii)* if \mathcal{G} is not an (approximate) k -regular graph, there is a set of agents that makes the metric $f(\mathcal{G}, k)$ decrease;
- iii)* if an agent joins or leaves the network, Algorithm 1 does not need to be re-initialized.

Conjectures

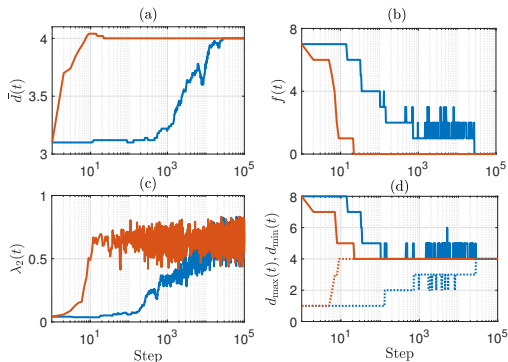
- ① if \mathcal{G} is an (approximate) k -regular graph, then the iterative execution of Algorithm 1 makes the graph a random (approximate) k -regular graph;
- ② the probability of getting the graph disconnected goes to zero as the number of nodes n and the degree k goes to infinity.

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Static networks and comparison with the state-of-art

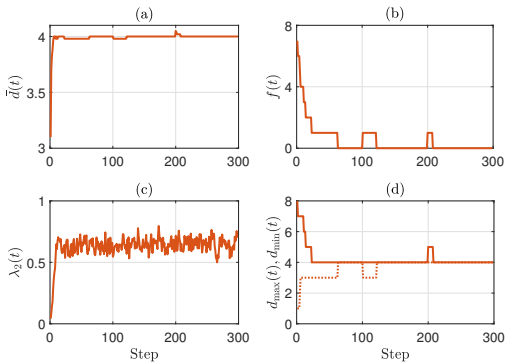
\bar{d} → average degree
 f → metric of regularity
 λ_2 → algebraic connectivity
 d_{\min}, d_{\max} → min/max degree



Blue curve: A. Y. Yazıcıoğlu, M. Egerstedt, and J. S. Shamma, "Formation of robust multi-agent networks through self-organizing random regular graphs", in *IEEE Transactions on Network Science and Engineering* (2015).

Open networks

\bar{d} → average degree
 f → metric of regularity
 λ_2 → algebraic connectivity
 d_{\min}, d_{\max} → min/max degree



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Conclusions and future directions

Contributions:

- A distributed protocol to self-organize any network into a regular graph with an arbitrary degree;
- Resiliency to open networks;

Future works:

- Provide a formal proof of randomness of the final time-varying network;
- Characterize the rate of convergence;
- ...



Diego

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Thank you for your attention!

Diego Deplano

Email: diego.deplano@unica.it

Webpage: <https://sites.google.com/view/deplanodiego/>